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#include <TinyGPS.h>
#include <LoRaWan.h>

TinyGPS gps;

char memBuffer[256];
char packetBuffer[51];

char DevEUI[] = "";
char AppEUI[] = "";
char devAddr[] = "";
char nwksKey[] = "";
char appSKey[] = "";
char AppKey[] = "";

#define LoraDeviceMode LWABP // LWOTA or LWABP
#define LoraDataRate DR0
// datarate SF/BW bits/s
// DR0 SF12/125KHz 250
// DR1 SF11/125KHz 440
// DR2 SF10/125KHz 980
// DR3 SF9/125KHz 1760
// DR4 SF8/125KHz 3125
// DR5 SF7/125KHz 5470
// DR6 SF7/250KHz 11000
// DR7 FSK:50kbps 50000
#define LoraPower 20
#define LoraPort 1
#define LoraADR 1
#define LoraNET 1 //1: Public net

#define DEBUG 1

void setup(void)
{
  if (DEBUG) {
    SerialUSB.begin(115200);
  }
  // while(!SerialUSB);

  Serial.begin(9600);
  lora.init();

  if (DEBUG) {
    memset(memBuffer, 0, 256);
    lora.getVersion(memBuffer, 256, 1);
    SerialUSB.print(memBuffer);
  }

  if (DEBUG) {
    memset(memBuffer, 0, 256);
    lora.getId(memBuffer, 256, 1);
    SerialUSB.print(memBuffer);
  }

  // Disable UART timeout
  memset(memBuffer, 0, 256);
  SerialLoRa.print("AT+UART=TIMEOUT, 0\r\n");
  if (DEBUG) {
    SerialUSB.print(memBuffer);
  }

  // Set public network key
  lora.setPubNetwKey(LoraNET);

  // NwksKey, AppSKey, AppKey
  lora.setKey(nwksKey, appSKey, AppKey);

  lora.setId(devAddr, DevEUI, AppEUI);
  if (DEBUG) {

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    SerialUSB.println();
}
lora.setReceiceWindowFirst(1);

//lora.setReceiceWindowSecond(869.525, DR3);

// Set RXwin2

memset(memBuffer, 0, 256);
SerialLoRa.print("AT+RXWIN2=869.525,DR3\r\n");
if (DEBUG) {
    SerialUSB.print(memBuffer);
}

lora.setPower(LoraPower);

lora.setDeciveMode(LoraDeviceMode);

lora.setChannel(0, 868.1, DR0, DR7);
//lora.setChannel(1, 868.3);
//lora.setChannel(2, 868.5);
lora.setChannel(1, 0);
lora.setChannel(2, 0);

lora.setDataRate(LoraDataRate, EU868);

lora.setPort(LoraPort);

if (DEBUG) {
    SerialUSB.println("Setup completed");
}
}

void loop(void)
{

    String packetString = "";

    packetString = get_gpsdata();
    if (DEBUG) {
        SerialUSB.println(packetString);
    }
    int strLength = packetString.length() + 1;

    packetString.toCharArray(packetBuffer, strLength);

    if (DEBUG) {
        SerialUSB.println("Start transmission");
    }

    bool result = false;
    result = lora.transferPacket(packetBuffer, strLength);
    if(result)
    {
        short length;
        short rssi;

        memset(memBuffer, 0, 256);
        length = lora.receivePacket(memBuffer, 256, &rssi);

        if (DEBUG) {
            if(length)
            {
                SerialUSB.print("Length is: ");
                SerialUSB.println(length);
            }
        }
    }
}

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        SerialUSB.print("RSSI is: ");
        SerialUSB.println(rssi);
        SerialUSB.print("Data is: ");
        for(unsigned char i = 0; i < length; i ++)
        {
            SerialUSB.print("0x");
            SerialUSB.print(memBuffer[i], HEX);
            SerialUSB.print(" ");
        }
        SerialUSB.println();
    }
}

delay(120*1000);
}

String get_gpsdata() {
    bool newData = false;
    String returnString = "";
    float flat, flon;
    unsigned long age;

    // For one second we parse GPS data and report some key values
    for (unsigned long start = millis(); millis() - start < 1000;)
    {
        while (Serial.available())
        {
            char c = Serial.read();
            // Serial.write(c); // uncomment this line if you want to see the GPS data flowing
            if (gps.encode(c)) // Did a new valid sentence come in?
                newData = true;
        }
    }

    if (newData)
    {
        gps.f_get_position(&flat, &flon, &age);
        returnString = "LAT=";
        returnString += String(flat, 6);
        returnString += " LON=";
        returnString += String(flon, 6);
        returnString += " SAT=";
        returnString += String(gps.satellites());
        returnString += " PREC=";
        returnString += String(gps.hdop());
        returnString += " AGE=";
        returnString += String(age);
    } else {
        returnString = "NO GPS data available!";
    }

    return returnString;
}

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